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In the Navy's search to find a more cost-effective maintenance tool, the Naval Research Laboratory at Stennis Space Center, Mississippi developed an Expert Maintenance Advisor for the AN/USH-32(V) Signal Data Recorder-Reproducer Set. This analog tape recorder system is a high performance acoustic data recorder/reproducer set used in data acquisition and data processing. Its maintenance is complicated by multiple adjustments, their relationships, and lengthy calibration and checkout procedures. The Expert Maintenance Advisor is a reference aid which has expert knowledge and the complete technical manual (text and graphics) embedded in a PC-based computer that is portable and user friendly. This paper discusses its development, knowledge engineering process and maintenance diagnosis capability.

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Expert Maintenance Advisor Development For Navy Shipboard Systems

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ABSTRACT

In the Navy's search to find a more cost-effective maintenance tool, the Naval Research Laboratory at Stennis Space Center, Mississippi developed an Expert Maintenance Advisor for the AN/USH-32(V) Signal Data Recorder-Reproducer Set. This analog tape recorder system is a high performance acoustic data recorder/reproducer set used in data acquisition and data processing. Its maintenance is complicated by multiple adjustments, their relationships, and lengthy calibration and checkout procedures. The Expert Maintenance Advisor is a reference aid which has expert knowledge and the complete technical manual (text and graphics) embedded in a PC-based computer that is portable and user friendly. This paper discusses its development, knowledge engineering process and maintenance diagnosis capability.

Introduction

The Navy has numerous shipboard systems which require corrective/preventive maintenance. Sailors and in-service engineering agents (ISEA) from Navy field activities perform these maintenance tasks using paper technical manuals and the associated test equipment while in port or at sea. Four problems associated with performing these maintenance tasks are:

- 1) Personnel Availability
- 2) Labor Intensive Test and Checkout Procedures
- 3) Absence of System Test Tapes
- 4) Costs

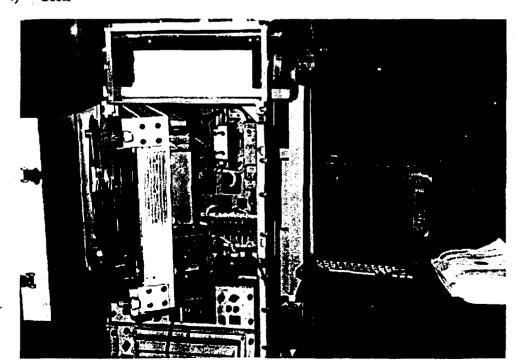


Figure 1. Recorder-Reproducer, Expert Maintenance Advisor and Conventional Maintenance Manuals. 1 Journal of the Conventional Maintenance Manuals.

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The EMA was developed to best meet Navy needs and support fleet readiness requirements. It is a PC-based reference aid which uses embedded subject matter expert knowledge to assist sailors with maintenance related tasks and provides heuristics which increase rather than remove or replace theirability to maintain Navy systems in a fully operational status. This Expert Systems technology application not only reduces maintenance costs but increases maintenance personnel skill level and system diagnosis turnaround time. The EMA is an intelligent reference aid not an electronic technical manual or automated page turner.

The first Expert Systems technology application (Figure 1) was the AN/USH-32(V) Signal Data Recorder-Reproducer (SRRS). It is menu driven (Figure 2) and provides facilities for rule-based language input, debugging, editing and testing. The Expert Maintenance Advisor is most valuable to maintenance personnel during maintenance turn-on procedures, troubleshooting and system diagnostics. It uses embedded subject matter expertise to guide them through a logical sequence of maintenance actions by incorporating "tricks of the trade" and "rules of thumb" in a reference section. Indexing, hypertext and direct table access are features visible on all screen displays for instantaneous access to technical manual references and graphics. These features alone make the EMA a complete reference aid for rapid maintenance actions.

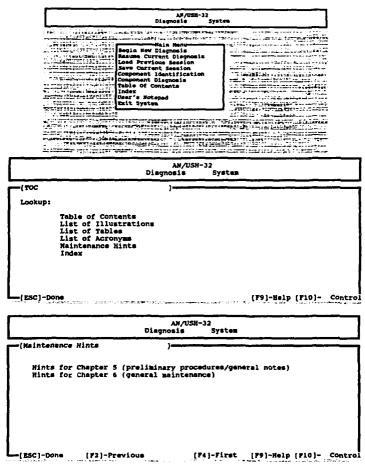


Figure 2. System Configuration

The system is hosted on a laptop computer running in a 4.01 or higher DOS environment. It requires a 120 MB hard drive and 4 MB of RAM which includes 3 MB extended RAM for storage and quick retrieval of textual data and graphics. Hypertext and highlighting features are included for all technical manual references during system diagnosis (AN/USH-32(V) Expert Maintenance Advisor User's Guide, 1992).

Expert Systems Development Approach

A rule-based language is used to develop and debug the EMA's knowledge. A maintainable rule-based language defines the encoded domain knowledge, which in turn is processed by an inference engine. (Alphonso, 1989) The expert system shell is written in a conventional programming language, C, which manipulates the knowledge with rules, facts, goals and a backward chaining inference mechanism. The heart of the system is embedded in a set of library routines. These routines are designed such that there is a close integration between the rule-based language and the source code, yet the two can be

developed independent of each other. A programmer can design the source code so that it uses the rule language to its fullest extent without knowing what rules are being used.

Library routines are callable from a conventional programming language to design, encode, debug and maintain knowledge. They manipulate the knowledge with an expert system shell independent of the conventional programming language. The static nature of the conventional programming language and the dynamics of the knowledge base make development and implementation independently unique for the knowledge base and source code development process.

Knowledge Engineering

Simply acquiring expert knowledge isn't enough, the approach to knowledge engineering is the true success to knowledge base development. The EMA does use existing knowledge, the technical manual, to make the knowledge engineering productive. The maintenance procedure flow diagram was used as the foundation to build the knowledge base. It includes every fact in its original format from the technical manual. The knowledge acquisition sessions provided a mechanism to format the knowledge presentation, refine knowledge information, design and implement source code and test and validate the EMA performance. (Kearney, 1990)

The knowledge acquisition sessions were conducted with ISEA representatives at the Naval Undersea Warfare Center (NUWC) in Norfolk, Virginia using troubleshooting and corrective maintenance sections from the technical manuals as the knowledge presentation format. Knowledge is represented as a set of complex data structures which consists of pointers to a linked list of objects. The technical manual is the primary knowledge base development source. It includes the objects, their pointers and attributes in the form of rules, facts and goals which determine the optimal resolution to an EMA system diagnosis. The maintenance turn- on, corrective maintenance and troubleshooting procedures are enhanced by the availability of knowledge engineering acquisition input from subject matter experts. The knowledge engineering input is embedded in a helpful hints section to insure that the technical manual retains its originality. This knowledge engineering approach makes subject matter expertise readily available and easy to update.

Initial operational suitability tests were conducted at the NUWC and the Fleet AntiSubmarine Warfare Training Center Pacific (FLEASWTRACENPAC) to validate EMA Version 1 for fleet readiness. A applemental fault isolation procedure to reduce in-fleet maintenance/alignment deficiencies is proposed for EMA Version 2. This proposed enhancement can be achieved with the development of a pre-recorded test tape. The pre-recorded test tape serves as an alignment tool for DIRECT/FM reproduce electronics and the capstan servo system. Test and alignment requirements can also be provided for the record electronics. Troubleshooting diagrams that perform true fault isolation and waveforms of actual properly adjusted signals at test points can be a part of the test/checkout procedure.

System Diagnosis Capability

The EMA's system diagnosis capabilities include:

- 1) Start To Finish Diagnosis
- 2) Specific Component Diagnosis
- 3) Save and Load Session Diagnosis

It can assist maintenance personnel with system maintenance from start to finish with or without previous knowledge of problem. In this diagnosis mode, the EMA relies on the sailor to observe and report the status of lamps, circuit breakers and motor movements to isolate the system fault. If the sailor suspects a problem in a specific component, the interactive troubleshooting and fault localization process can begin at that point in the logic diagram flow. Figure 3 shows an excerpt from the logic flow diagram and its source code rules. Interruptions or detail to other mission critical tasks may require that the sailor terminate an EMA session. If this happens, this session can be saved at that point and reloaded at the same point later. The addition of a Helpful Hints section gives sailors the benefit of having an expert by their side at all times in any system diagnosis mode. Appendix A is an example of a demonstration scenario using the EMA.

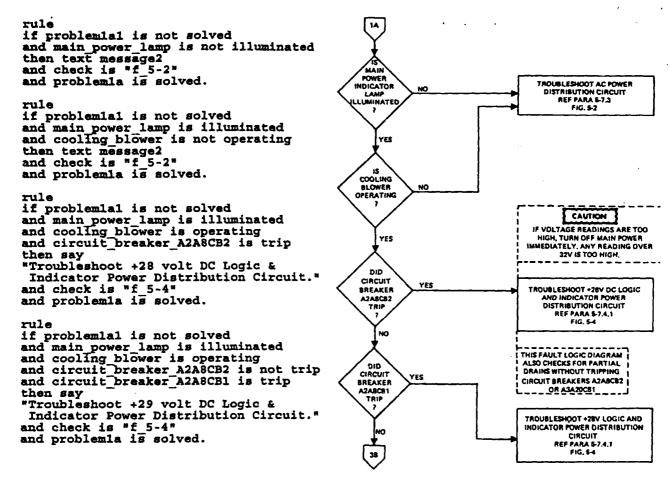


Figure 3. Troubleshooting Flow Chart and Rule Source Code

Summary

The Expert Maintenance Advisor makes a significant impact on the AN/USH-32's operational availability for data acquisition and data processing. It is an intelligent shipboard maintenance capability that provides on-line expert knowledge in a small portable package. Cost savings to the Navy in terms of time and service requests to Navy field activities and other commercial vendors will be substantial.

The Expert Maintenance Advisor has received numerous accolades during its debut in the training community. Several suggested improvement features from the training community were incorporated in Version 1 after visits with Naval personnel at the FLEASWTRACENPAC in San Diego, California. It was also exhibited at the First World Congress On Expert Systems held in Orlando, Florida, December, 1991. The Expert Maintenance Advisor saga continues while the Navy's new maintenance capability sets the pace as the "wave of the future" ashore and afloat.

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Technical Manual For Sonar Data Recorder-Reproducer Set AN/USH-32(V), Volume 2, SE314-GV-MMM-02A, Change A, 1 MAY 88

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APPENDIX A

AN/USH-32 Expert Maintenance Advisor Demonstration Scenario

This demonstration diagnoses a fault in the detection assembly and advises the sailor to replace the End-of-tape/ Beginning-of-tape (EOT/BOT) A2A2A3. It sequences through functional observations, checks voltage levels and provides screen text/graphics information to the sailor during maintenance. Text and graphic excerpts from the system demonstration are listed with the interactive response shown in **bold**.

New Diagnosis - Main menu selection

Not Turns - Indicates the response to capstans motion

Illuminated - Indicates the response to main power lamp illumination

Operating - Indicates the response to cooling blower operation

None - Indicates the response to tripped circuit breakers

28 Volts - Indicates the response to the voltage meter reading

20 Volts - Indicates the response to the voltage meter reading

5 Volts - Indicates the response to the voltage meter reading

Not 15 Volts - Indicates the response to the voltage meter reading

Return - Message to troubleshoot the +15 volt Transport Power Distribution Circuit

Not Corrected - The alignment procedure does not correct the fault. If the sailor needs further details, they are available on the screen in paragraph p_6-2-2. P_6-2-2 references figure f_6-1 which is also available on the screen. Thesescreen outputs are accessible using hypertext features.

15 Volts - Indicates the response to the voltage meter reading

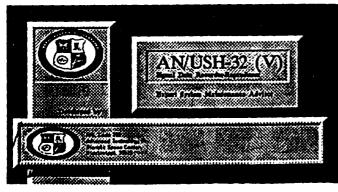
15 Volts - Indicates the response to the voltage meter reading

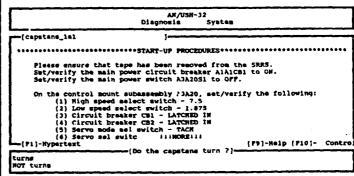
Not 15 Volts - Indicates the response to the voltage meter reading

15 Volts - Indicates the response to the voltage meter reading

Return - Advises the sailor to replace A2A2A3 detection assembly and provides a cross reference to the part number, manufacturer's address and installation/removal procedures

Return - Advises the sailor to perform the complete maintenance turn-on procedure to verify the SRRS's operational status





AM/MMM-32 Diagnosis System	AN/USR-32 Diagnosis System	
(main_power_lamp)	[voltage_meter_5v]	
Please check the main power lamp to determine if it is illuminated.	Please set voltage check switch A3A20814 to +5 volts. How observe the voltage check meter to see if it indicates 5 volts.	
	the voltage check seter to see it it indicates a voltage.	
	į	
[71]-Hypertext [79]-Help [710]- Contro	[F1]-Hypertext [F9]-Help [F10]- Control	
[Is the main power lemp illuminated?]	[Is the voltage meter 5v?]	
NOT illuminated	NOT 5V	
AM/USH-32 Diagnosis System	AM/USH-32 Diagnosis System	
[cooling_blower]-	[#oltage_meter_15v_xport]	
IS THE COOLING BLOWER OPERATING?	Please set voltage check switch A3A20514 to +15 volts xport. Now	
	observe the voltage check meter to see if it indicates 15 volts.	
]	
(91) Manage (91) Mark (91) Mark (91)		
[F1]-Hypertaxt [F3]-Hext [F9]-Help [F10]- Contro	[Is the voltage meter 15v?]	
operating NOT operating	NOT 15V	
AM/USH-32 Diágnosis System		
(circuit_breaker_tripped)		
Please observe the status of the following circuit breakers	AN/USH-32 Diagnosis System	
to determine if they are tripped or not.		
circuit breaker AlASCB1 circuit breaker AlASCB2	A STATE OF THE PROPERTY OF THE	
circuit breaker AlASCB3 circuit breaker AlASCB4	The Branch of the second second of the secon	
CAUTION!	The process of the pr	
If voltage readings are too high, turn off main power immediately. Any reading over 32 volts is considered to be too high.	Troubleshoot the +15 wolt Transport Power Distribution Circuit.	
[71]-Hypertext [79]-Help [710]- Contro.		
AZANCB2 [Which circuit breaker is tripped?]		
A2ABCB1 none		
	·	
AM/USE-32 Diagnosia System	AM/USM-32 Diagnosis System	
-{voltage_meter_28v }-	(f_5-6_fault)	
Please set voltage check switch ADA20514 to 28 volts. Now observe the voltage check meter to see if it indicates 28 volts.	o Please perform the alignment procedure described in paragraph p_6-2-2.	
	IS THE FAULT CORRECTED?	
[71]-Hypertext [79]-Help [710]- Control		
[Is the voltage meter 28v?]	corrected [Is the fault corrected?]	
NO. 384	NOT corrected	
AN/USH-32	AW/USM-32	
Diagnosis System	Diagnosis System	
voltage_meter_20v_2b	(P_6-2-2	
Please set voltage check ewitch AJA20514 to +20 volts servo. Now observe the voltage check meter to see if it indicates 20 volts.	REGULATOR AND SERVO POMER AMPLIFIER. (See fig f_6-1.) To adjust the voltage regulator circuit on regulator and servo power amplifier APAL, proceed as folio-2.	
	a. Secure the isolation mount safety latch. Open the dust cover and	
	secure it in the open position with the safety latch. Load a reel of clean, degaussed tape.	
1	b. Open transport assembly A2 to the fully open position and engage the transport safety latch.	
1	G. Press the MATH POWER switch to the CM position. Press the READY- LOAD switch to the READY position.	
[F9]-Help [F10]- Control	d, See fig f_6-1 and c ///HORBILL ultimeter between A2TP5 [F4]-Henu [F2]-Previous [F4]-Pirst [F9]-Nelp [F10]- Control	
200 [Is the voltage mater 20v?]	corrected [Is the fault corrected]	
NOT 20V	NOT corrected	

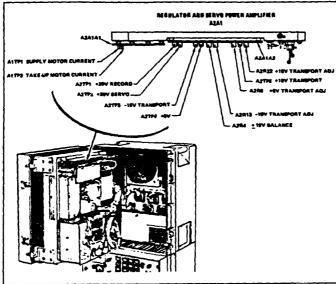


Figure 6-1. Regulator and Servo Power Amplifier A2A?, Location of Tost Points and Adjustments

- a. Secure the isolation mount safety fatch. Open the dust cover and secure it in the open position with the safety latch.
- b. Open the transport assembly A2 to the fully open position and engage the transport safety latch.
- c. Open the hinged cover on the control mount A3.
- d. Frem the MAIN POWER switch to the ON position.
- e. See figure 6-2 and connect the digital multimeter between TPI (+) and TP2 (ground). Verify that the meter indicates +15 ±0.005 volts. If this reading is not obtained, adjust variable resistor R6.
- f. Connect the digital smultimeter between TPJ (-) and TPZ (ground). Verify that the meter indicates -15 ±0.005 value. If this reading is not obtained, adjust variable reactor Rii.
- g. Connect the digital multimeter between TP1 (+) and TP2 (ground) and adjust variable resistor R6 to reduce the +15V by 30 millivolts (+14.950 \pm 0.005 volts).
- h. Connect the digital nunitimense to TF3 (-) and TF2 (ground) and verify that the reading has been reduced by 50 millivels (-14.950 ±0.005 volts). If this reading is not obtained, edges variable resistor R10 to obtain the necessary reduction in the reading.

AM/USH-32 Disgnosis System AR/USH-32 Diagnosis System -[f_5-0_Bultimeter -[f_5-0e_voltage_meter o Piesse press the main power switch to OFF. o Please press the main power switch to OFF. Disconnect connectors A2ASP? from A2A2J? on control logic assembly, A2ASPI from A2A7A3JJ2 on record amplifier assembly and A1A3P4 from A2ASJ2 on connector mounting bracket (SEE Eig ±3-78). o Then reconnect A2A8P7 to A2A2J2 on the control logic assembly. o Press the main power switch back to OM. Connect a multimeter between TP5 (+15) and chassis ground on voltage regulator and servo power amplifier A2A1 (SEE fig f_6-1). DOES THE VOLTAGE CHECK HETER INDICATE 15 VOLTS? o Press the main power switch to OW. DOES THE MULTIMETER INDICATE +15 VOLTS DC? -{Is the multimeter +15v DC?}-Melp [F10]- Control -{ P1 }-Hypertext -[P1]-Hypertext (F9]-Help [F10]- Control +15V DC NOT +15V DC -{ Is the voltage meter 15v?}-15V NOT 15V

6-2

AZABJY on connector mounting bracket (SEE fig f_5-78).

o Connect a multimater between TP5 (+15) and chassis ground on voltage regulator and serve power amplifier A2Al (SEE fig f_6-1).

o Press the main power switch to OW.

DOES THE MULTIMETER INDICATE +15 VOLTS DC7

[F1]-Nypertext [Is the multimeter +15v DC7]

AM/USH-32

Diagnosis System

[f_5-8b_voltage_mater]

o Please press the main power switch to OFP.

o Reconnect A1A3P4 to A2ABJ2 on connector mounting bracket.

o Press the main power switch back to OM.

DOES TWE VOLTAGE CHECK METER INDICATE 15 VOLTS?

[F1]-Rypertext [F9]-Help [F10]- Control 15v/

MOT/ 15v/

MOT/ 15v

NAM/DEN-32 Diagnosis System	
-[f_5-8f_voltage_neter]	AF/DEE-12 Diagnosis System
o Please press the main power switch to Off.	F=(I(.5-6-1)
o Reconnect connector A2A7A31J2.	Please replace BOT/BOT A2A4A3 with a spare.
o Remove MOT/BOT A2A2A3 from the control logic assembly A2A2 (SEE figs fig f_6-37 and fig f_6-7).	MET 14028, part no. 541099 PERFORM COMPLETE MAINTENANCE TURN-ON PROCEDURE.
o Press the main power switch to CH.	į.
DOES THE VOLTAGE CERCK HETER INDICATE 15 VOLTS?	
[F1]-Hypertext [Is the voltage meter 15v?] (F9]-Help (F10]- Control NOT 15v	[ESC]-Done [F7]-Help [F10]- Contro

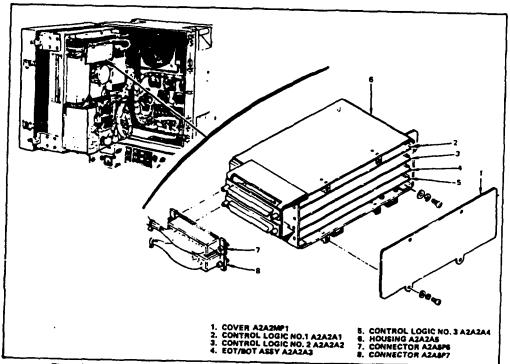


Figure 6-48. Control Logic Assembly A2A2, Removal and Installation Procedures (Sheet 1 of 2)

Table 7-2. Signal Data Recorder-Reproducer Set AN/USH-32(V)1 AN/USH-32(V)2 Part No. 541000-0001 or 541000-0002

Reference Designation	Notes	Name and Description	Figure Number (Item)
IA1A2A2A3	0	EOT/BOT Detection Assy mfr 14028, part no. 541099	6-48(4)
Table 7-5. List of	of Manufact	urers	
Mfr Code		Name and Address	
14028		DATATAPE Incorporated A Kodak Company 360 Sierra Madre Villa Avenue	

Pasadena, CA 91109